# Are the Weak Measurements Really Measurements? 

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Editors: Danko Georgiev \& Stefano Ansoldi
Article history: Submitted on April 16, 2013; Accepted on May 14, 2013; Published on May 15, 2013.

Weak measurements can be seen as an attempt at answering the Which way? question without destroying interference between the pathways involved. Unusual mean values obtained in such measurements represent the response of a quantum system to this forbidden question, in which the true composition of virtual pathways is hidden from the observer. Such values indicate a failure of a measurement where the uncertainty principle says it must fail, rather than provide an additional insight into physical reality.
Quanta 2013; 2: 50-57.

## 1 Introduction

Twenty five years ago Aharonov, Albert and Vaidman published a paper entitled "How the result of a measurement of a component of the spin of a spin- $\frac{1}{2}$ particle can turn out to be 100" [1]. The authors' idea was further developed in a large volume of work on the so-called weak measurement (see, for example, [ $2,-10]$ ), culminating in a somewhat bizarre report by the British Broadcasting Corporation (BBC) [11] suggesting that "pioneering experiments have cast doubt on a founding idea of the branch of physics called quantum mechanics". There seems to

[^0]be room for discussion about what actually happens in a weak measurement, and this is the subject of this paper. Some of the early and more recent criticism of the original approach used in [1] can be found in [12--17].

There appear to be only two possible answers to the original question posed by the authors of [1]: (1) there is a new counterintuitive aspect to quantum measurement theory, or (2) the interpretation of the result of the measurement is flawed. In this paper we will follow [14] in advocating the second point of view. The argument is subtle. There is no error in the simple mathematics of [1]. It is the interpretation of the result which is at stake.

Below we will argue that weak measurement could be viewed as an attempt to answer the Which way? question without destroying interference between the pathways of interest. Such an attempt, however, must fail as a consequence of the uncertainty principle [18, 19] and the unusual results that can be obtained for weak values are just the evidence of this failure.

## 2 Probabilities and negative probabilities

A random variable $f$ is fully described by its probability distribution $\rho(f)$. Often it is sufficient to know only the typical value of $f$, and the range over which the values are likely to be spread. To get an estimate for the centre and the width of the range, one usually evaluates the mean
value of $f$, given by

$$
\begin{equation*}
\langle f\rangle=\frac{\int f \rho(f) d f}{\int \rho(f) d f} \tag{1}
\end{equation*}
$$

and the standard mean deviation

$$
\begin{equation*}
\sigma=\sqrt{\left\langle f^{2}\right\rangle-\langle f\rangle^{2}} \tag{2}
\end{equation*}
$$

Suppose $f$ can only take the values 1 and 2 , and its unnormalised probability distribution is $\rho(1)=1.1$ and $\rho(2)=1$. We, therefore, have

$$
\begin{equation*}
\langle f\rangle=\frac{[1 \times \rho(1)+2 \times \rho(2)]}{[\rho(1)+\rho(2)]} \approx 1.4762 \tag{3}
\end{equation*}
$$

which reasonably well represent the centre and width of the interval $[1,2]$ containing the values of $f$.

Suppose next that, for whatever reason, the unnormalised probabilities were allowed to take negative values, for example

$$
\begin{align*}
& \rho(1)=-1.1  \tag{4}\\
& \rho(2)=1
\end{align*}
$$

Using the same formulas, we find

$$
\begin{align*}
\langle f\rangle & =-9  \tag{5}\\
\sigma & \approx 10.49_{\imath}
\end{align*}
$$

which, clearly, no longer describe the range [1,2], since $|\langle f\rangle|$ is too large, and $\sigma$ is purely imaginary. The reason for obtaining such an anomalous mean value is that the denominator in Equation 3 is small, while the numerator is not - hence the large negative expectation value in Equation 5

In general, the mean and the standard mean deviation of an alternating distribution do not have to represent the region of its support. These useful properties of $\langle f\rangle$ and $\sigma$ are lost, once a distribution is allowed to change its sign.

## 3 Complex-valued distributions

To make things worse, let us assume that the unnormalised probabilities $\rho(f)$ are also allowed to take complex values

$$
\begin{equation*}
\rho(f)=\rho_{1}(f)+\iota \rho_{2}(f) \tag{6}
\end{equation*}
$$

while $f$ may take any value inside the interval $[a, b]$. As before, we will construct a normalised distribution

$$
\begin{equation*}
w(f) \equiv \frac{\rho(f)}{\int_{a}^{b} \rho\left(f^{\prime}\right) d f^{\prime}} \tag{7}
\end{equation*}
$$

which can now be written as a sum of its real and imaginary parts

$$
\begin{gather*}
w(f) \equiv w_{1}(f)+\imath w_{2}(f)  \tag{8}\\
=\frac{A_{1}^{2}\left(\rho_{1}(f) / A_{1}\right)+A_{2}^{2}\left(\rho_{2}(f) / A_{2}\right)}{A_{1}^{2}+A_{2}^{2}} \\
+\imath A_{1} A_{2} \frac{\rho_{2}(f) / A_{2}-\rho_{1}(f) / A_{1}}{A_{1}^{2}+A_{2}^{2}} \tag{9}
\end{gather*}
$$

where

$$
\begin{equation*}
\int_{a}^{b} \rho(f) d f=A_{1}+\imath A_{2} \tag{10}
\end{equation*}
$$

Now we may wonder whether the value of $\operatorname{Re}\langle f\rangle=$ $\int_{a}^{b} f w_{1}(f) d f$ would give us an idea about the location of the interval $[a, b]$. From Equation 8 we note that if both $\rho_{1}(f)$ and $\rho_{2}(f)$ do not change sign, $w_{1}(f)$ is a proper probability distribution, and its mean certainly lies within the region of its support. If, on the other hand, both $\rho_{1}(f)$ and $\rho_{2}(f)$ alternate, the mean $\operatorname{Re}\langle f\rangle$ is allowed to lie anywhere, and may not tell us anything about the actual range of values of $f$.

So here is how a confusion might arise: suppose one needs to evaluate the average of a variable known to take values between 1 and 2 indirectly, i.e., without checking whether the distribution alternates, or is a proper probabilistic one. Obtaining a result of -9 may seem unusual, until it is realised that the employed distribution changes sign, and scrambles the information about the actual range values involved.

One remaining question is why was it necessary to employ such a tricky distribution in the first place?

## 4 Feynman's uncertainty principle and the Which way? question

A chance to employ oscillatory complex-valued distributions is offered by quantum mechanics, and for a good reason. Consider a kind of double-slit experiment in which a quantum system, initially in a state $|I\rangle$, may reach a given final state $|F\rangle$ via two pathways, the corresponding probability amplitudes being $A(1)$ and $A(2)$. There are two possibilities.

Case (1). The pathways interfere, and the probability to reach $|F\rangle$ is given by

$$
\begin{equation*}
P^{F \leftarrow I}=|A(1)+A(2)|^{2} \tag{11}
\end{equation*}
$$

Case (2). Interference between the pathways has been completely destroyed by bringing the system in contact with another system, or an environment. Now the probability to reach $|F\rangle$ is

$$
\begin{equation*}
P^{F \leftarrow I}=|A(1)|^{2}+|A(2)|^{2} \tag{12}
\end{equation*}
$$

The two cases are physically different, as are the two probabilities. In the second case the two pathways are real. One can make an experiment which would confirm by multiple trials that the system travels either the first or the second route with frequencies proportional to $|A(1)|^{2}$ and $|A(2)|^{2}$, respectively. In the first case the individual pathways remain virtual. Together they form a single real pathway travelled with probability $|A(1)+A(2)|^{2}$, and there is no way of saying, even statistically, which of the two virtual paths the system has actually travelled.

The above leads to a loose formulation of the uncertainty principle [18]: several interfering pathways or states should be considered as a single unit. Quantum interference erases detailed information about a system. This information can only be obtained if interference is destroyed, usually at the cost of perturbing the system's evolution, thus destroying also the very studied phenomenon, e.g., an interference pattern in Young's double-slit experiment.

## 5 Feynman paths and pathways

Let us discuss the pathways in a slightly more formal way. By slicing the time interval into $N$ subintervals, and sending $N$ to infinity, we can write the transition amplitude for a system with a Hamiltonian $\hat{H}$ as a sum over paths traced by a variable $\hat{A}$ :

$$
\begin{array}{r}
\langle F| e^{-l \hat{H} t / \hbar}|I\rangle=\lim _{N \rightarrow \infty} \sum_{k_{1}, k_{2}, \ldots k_{N+1}}\left\langle F \mid a_{k_{N+1}}\right\rangle \\
\times\left\langle a_{k_{N+1}}\right| e^{-l \hat{H} t / \hbar N}\left|a_{k_{N}}\right\rangle\left\langle a_{k_{N}}\right| \ldots\left|a_{k_{2}}\right\rangle \\
\times\left\langle a_{k_{2}}\right| e^{-l \hat{H} t / \hbar N}\left|a_{k_{1}}\right\rangle\left\langle a_{k_{1}} \mid I\right\rangle \\
\equiv \sum_{\text {paths }} A^{F \leftarrow I}[\text { path }] \tag{13}
\end{array}
$$

where $a_{k}$ and $\left|a_{k}\right\rangle$ are the eigenvalues and eigenvectors of the variable of interest $\hat{A}, \hat{A}\left|a_{k}\right\rangle=a_{k}\left|a_{k}\right\rangle$. We also introduced Feynman paths: functions which take the values $a_{k}$ from the spectrum of $\hat{A}$ at each discrete time. In the limit $N \rightarrow \infty$ we will denote such a path by $a(t)$. The paths are virtual pathways, each contributing a probability amplitude $A^{F \leftarrow I}$ [path] defined in Equation 13. In the chosen representation they form the most detailed complete set of histories available to the quantum system.

We may be interested not in every detail of the particle's past, but only in the value of a certain variable, a functional defined for a Feynman path $a(t)$ as an integral

$$
\begin{equation*}
\mathcal{F}[\text { path }]=\int_{0}^{t} \beta\left(t^{\prime}\right) a\left(t^{\prime}\right) d t^{\prime} \tag{14}
\end{equation*}
$$

where $\beta(t)$ is a known function of our choice. We can define a less detailed set of virtual pathways by grouping
together those paths for which the value of $\mathcal{F}[a]$ equals some $f$. Each pathway now contributes the amplitude

$$
\begin{equation*}
\Phi^{F \leftarrow I}(t \mid f)=\sum_{\text {paths }} \delta(f-\mathcal{F}[\text { path }]) A^{F \leftarrow I}[\text { path }] \tag{15}
\end{equation*}
$$

where $\delta(z)$ is the Dirac delta. The new pathways contain the most detailed information about the variable $\mathcal{F}$, while information about other variables has been lost to interference in the sum given by Equation 15 .

Next, we can define a coarse-grained amplitude distribution $\Psi$ for $\mathcal{F}$ by smearing $\Phi^{F \leftarrow I}(t \mid f)$ with a window function $G(f)$ :

$$
\begin{equation*}
\Psi^{F \leftarrow I}(t \mid f)=\int G\left(f-f^{\prime}\right) \Phi^{F \leftarrow I}\left(t \mid f^{\prime}\right) d f^{\prime} \tag{16}
\end{equation*}
$$

With $G(f)$ chosen, for example, to be a Gaussian of a width $\Delta f$ we are unable to distinguish the values $f_{1}$ and $f_{2}$ less than $\Delta f$ apart, $\left|f_{1}-f_{2}\right| \lesssim \Delta f$, since the corresponding pathways may now interfere.
The coarse-graining does, however, have a physical meaning. Consider a basis $\{F\}$ containing our final state $|F\rangle$, and construct a state $\left|\Psi^{I}(t \mid f)\right\rangle \equiv \sum_{F}|F\rangle \Psi^{F \leftarrow I}(t \mid f)$ so that $\Psi^{F \leftarrow I}(t \mid f)=\left\langle F \mid \Psi^{I}(t \mid f)\right\rangle$. It is easy to check [20] that $\left.\Psi^{I}(t \mid f)\right\rangle$ satisfies a differential equation

$$
\begin{equation*}
\imath \partial_{t}\left|\Psi^{I}(t \mid f)\right\rangle=\left[\hat{H}-\imath \hbar \partial_{f} \beta(t) \hat{A}\right]\left|\Psi^{I}(t \mid f)\right\rangle \tag{17}
\end{equation*}
$$

with the initial condition

$$
\begin{equation*}
\left|\Psi^{I}(t=0 \mid f)\right\rangle=G(f)|I\rangle \tag{18}
\end{equation*}
$$

This can also be seen as a Schrödinger equation describing a system interacting with a von Neumann pointer [21] whose position is $f$. With it we have the recipe for measuring the the quantity $\mathcal{F}$ [path]: first prepare the system in the initial state $|I\rangle$ and the pointer in the state $\int G(f)|f\rangle d f$. Switch on the coupling, and at a time $t$ measure the pointer position accurately. Interference between paths with different values of $\mathcal{F}$ [path] will be destroyed, since they lead do different pointer positions.

## 6 The accuracy and the back-action

Our measurement scheme has an important parameter, the width of the window $G(f), \Delta f$, which determines the extent to which we can ascertain the value of $\mathcal{F}$ [path], once the pointer has been found in $f$. This accuracy parameter also determines the perturbation a measurement exerts on the measured system. This, in turn, can be judged by how much the probability to arrive in a final states $|F\rangle$ with the meter on differs from that with the meter off. The former is given by

$$
\begin{equation*}
P^{F \leftarrow I}(t)=\int\left|\Psi^{F \leftarrow I}(t \mid f)\right|^{2} d f \tag{19}
\end{equation*}
$$

and, in general, is not equal to $\left.\left|\langle F| e^{-l \hat{H} t / \hbar}\right| I\right\rangle\left.\right|^{2}$ since

$$
\begin{array}{r}
\int G\left(f-f^{\prime}\right) \Phi^{F \leftarrow I}\left(t \mid f^{\prime}\right) d f^{\prime} \neq G(f)\langle F| e^{-l \hat{H} t / \hbar}|I\rangle \\
G(f)\langle F| e^{-l \hat{H} t / \hbar}|I\rangle=G(f) \int \Phi^{F \leftarrow I}\left(t \mid f^{\prime}\right) d f^{\prime} \tag{21}
\end{array}
$$

where the last equality is obtained by integrating Equation 15

The perturbation can be minimised by choosing $G(f)$ to be very broad. By construction, the value of $\mathcal{F}$ typically lies within a finite interval, say, $a \leq \mathcal{F}$ [path] $\leq b$, outside of which $\Phi^{F \leftarrow I}\left(t \mid f^{\prime}\right)$ vansihes. A very broad $G\left(f-f^{\prime}\right)$ can, therefore be replaced by $G(f)$, making the left-hand side of Equation 20 proportional to $\langle F| e^{-l \hat{H} t / \hbar}\left|\Psi_{0}\right\rangle$.

Thus, in order to study the system with the interference between the pathways intact, we must make a highly inaccurate weak measurement. This can be achieved by introducing a high degree of uncertainty in the pointer's initial position. The following classical example may give us some encouragement.

## 7 Inaccurate classical

## measurements

Consider a classical system which can reach a final state in several different ways. Let us say, a ball can roll from a hole $I$ to a hole $F$ down the first groove with the probability $w_{1}>0$, or down the second groove, with the probability $w_{2}>0$, and so on. It is easy to imagine a purely classical pointer which moves one unit to the right if the ball travels the first route, or two units to the right, if the second route is travelled, and so on. The meter is imperfect: we can accurately determine its final position, while we cannot be sure that it has been set exactly at zero. Rather, its initial position is distributed around 0 with a probability density $G(f)$ of a zero mean and a known variance. Let there be just two routes. Now the final meter readings are also uncertain, with the probability to find it in $f$ given by

$$
\begin{gather*}
P^{F \leftarrow I}(f)=\int G\left(f-f^{\prime}\right) w\left(f^{\prime}\right) d f^{\prime}  \tag{22}\\
w(f) \equiv w_{1} \delta(f-1)+w_{2} \delta(f-2)
\end{gather*}
$$

If the meter is accurate, i.e., if $G(f)$ is very narrowly peaked around $f=0$, and if we perform $N$ trials, we will have just two possible readings: $f=1$ will be realized approximately $N w_{1}$ times and $f=2$ will be realized approximately $N w_{2}$ times.

Suppose next that the meter is highly inaccurate, and the width of $G, \Delta f$ is much larger than 1 . A simple
calculation shows [14] that the first two moments of the final distribution are given by

$$
\begin{array}{r}
\langle f\rangle=\int f w(f) d f  \tag{23}\\
\left\langle f^{2}\right\rangle=\int f^{2} w(f) d f+\frac{\int f^{2} G(f) d f}{\int G(f) d f}
\end{array}
$$

We have, therefore, a very broad distribution, whose mean coincides with the mean of $w(f)$. Since the second moment of $G$ is known, by performing a large number of trials we can extract from the data also the variance $\sigma$ of $w(f)$. For instance, if the two routes are travelled with equal probabilities, $w_{1}=w_{2}=\frac{1}{2}$, we have

$$
\begin{align*}
\langle f\rangle & =1.5  \tag{24}\\
\sigma & =0.5
\end{align*}
$$

From this we can correctly deduce that there are just two, and not three or four, routes available to the system, and that they are travelled with roughly equal probabilities. This simple example shows that, classically, even a highly inaccurate meter can provide some information about the alternatives available to a stochastic system. It is just a matter of performing a large number of trials required to gather the necessary statistics. Next we will see whether this remains true in the quantum case.

## 8 Inaccurate, or weak, quantum measurements

In the quantum case, employing an inaccurate meter has a practical advantage: we minimise the back-action of the meter on the measured system, and may hope to learn something without destroying the interference. As discussed in section 6, we can make a measurement noninvasive by giving the initial meter position a large quantum uncertainty (that is to say, we choose a pure meter state broad in the coordinate space). We prepare the system and the pointer in a product state, given by Equation 18, turn on the interaction, check the system's final state, and sample the meter reading provided this final state is $|F\rangle$. From Equation 17 the moments of the distribution of the meter readings are given by

$$
\begin{equation*}
\left\langle f^{n}\right\rangle \equiv \frac{\int f^{n}\left|\Psi^{F \leftarrow I}(t \mid f)\right|^{2} d f}{\int\left|\Psi^{F \leftarrow I}(t \mid f)\right|^{2} d f} \tag{25}
\end{equation*}
$$

As the width of the initial meter state $\Delta f$ tends to infinity, assuming $\operatorname{Im} G(f)=0$ we have [14]

$$
\begin{equation*}
\langle f\rangle=\operatorname{Re}(\bar{f})+O(1 / \Delta f) \tag{26}
\end{equation*}
$$

$$
\begin{gather*}
\left\langle f^{2}\right\rangle=\frac{\int f^{2} G(f)^{2} d f}{\int G(f)^{2} d f}+C\left(\operatorname{Re}\left(\bar{f} \bar{f}^{2}\right)-|\bar{f}|^{2}\right)  \tag{27}\\
+|\bar{f}|^{2}+O(1 / \Delta f)
\end{gather*}
$$

where $C$ is a factor of order of unity, which depends only on the shape of $G(f)$ [14], and we have introduced the notation $\bar{f}^{n}$ for the $n$-th moment of the complex-valued amplitude distribution $\Phi(f)$ defined in Equation 15

$$
\begin{equation*}
\bar{f}^{n} \equiv \frac{\int f^{n} \Phi^{F \leftarrow I}(t \mid f) d f}{\int \Phi(t \mid f) d f} \tag{28}
\end{equation*}
$$

It is at this point that improper averages (Equation 28) evaluated with oscillatory distributions enter our calculation, originally set to evaluate proper probabilistic averages (Equation 26). Expressions similar to Equation 26 have been obtained earlier in [1,4] for a weak von Neumann measurement and in [22] for the quantum traversal time. They are the quantum analogues of the classical Equation 23 .

We see that the quantum case turns out to be different in one important aspect. Where the inaccurate classical calculation of section 7 yields the mean of the probability distribution, its quantum counterpart gives us the mean evaluated with the probability amplitude $\Phi^{F \leftarrow I}(t \mid f)$. There is no a priori reason to expect that either its real or imaginary part does not change sign. As discussed in section 2 and section 3, such averages are not obliged to tell us anything about the actual range of a random variable. Thus, our attempt to answer the Which way? (Which $f$ ?) question is likely to fail, as we are not able to extract the information about the alternatives available to a quantum system. Because of the uncertainty principle, as long as the pathways remain interfering alternatives, the question that we are asking is not well posed.

## 9 A double slit experiment

To give our approach a concrete example, we return to the double slit experiment. Consider a two-level system, e.g., a spin- $\frac{1}{2}$ precessing in a magnetic field. The Hamiltonian is given by:

$$
\begin{equation*}
\hat{H}=\hbar \omega_{L} \hat{\sigma}_{x} \tag{29}
\end{equation*}
$$

where $\omega_{L}$ is the Larmor frequency, and

$$
\hat{\sigma}_{x}=\left(\begin{array}{ll}
0 & 1  \tag{30}\\
1 & 0
\end{array}\right)
$$

is the Pauli spin matrix. We assume that the spin is preselected in a state polarised along the $z$-axis at $t=0$, and then post-selected in the same state at $t=T$. We also wish to know the state of the spin half-way through the


Figure 1: Schematic diagram showing a Feynman path a(t) for a spin- $\frac{1}{2}$ precessing in a magnetic field. The path connects the state $|1\rangle$ at $t=0$ with the same state at $t=1.5659 / \omega_{L}$ (very close to $t=\pi / 2 \omega_{L}$ ). Between these times the path jumps between 1 and 2, passing through $|2\rangle$ at $t=\pi / 4 \omega_{L}$.
transition, at $t=T / 2$. We follow the steps outlined insection 5. At any given time, and in the given representation, the spin can point up or down the $z$-axis. We label these two states $|1\rangle$ and $|2\rangle$, respectively. Feynman paths are, therefore, irregular curves, as shown in Figure 1.

The functional $\mathcal{F}$ (path) is given by Equation 14 with $\beta\left(t^{\prime}\right)=\delta\left(t^{\prime}-T / 2\right):$

$$
\begin{equation*}
\mathcal{F}(\text { path })=\int_{0}^{t} \delta\left(t^{\prime}-T / 2\right) a\left(t^{\prime}\right) d t^{\prime}=a(T / 2) \tag{31}
\end{equation*}
$$

Thus, we combined the Feynman paths ending in the state $|1\rangle$ at $t=T$ into two virtual pathways, one containing the paths passing at $t=T / 2$ through the state $|1\rangle$, and the other containing the paths passing through the state $|2\rangle$. The corresponding probability amplitudes are those for evolving the spin freely from its initial state to $|1\rangle$ or $|2\rangle$ at $t=T / 2$, and then to the final state $|1\rangle$ at $t=T$ :

$$
\begin{align*}
& A(1)=\cos ^{2}\left(\omega_{L} T / 2\right)  \tag{32}\\
& A(2)=-\sin ^{2}\left(\omega_{L} T / 2\right)
\end{align*}
$$

We will need a meter. The interaction $-\imath \partial_{f} \delta(t-T / 2) \hat{A}$ corresponds to a von Neumann measurement [21] of the operator $\hat{A}=[1|1\rangle\langle 1|+2|2\rangle\langle 2|]$ performed at $t=T / 2$. The accuracy of the measurement depends on the width $\Delta f$ of the initial meter state, which we will choose to be a Gaussian:

$$
\begin{gather*}
G(f)=\left(2 / \pi \Delta f^{2}\right)^{\frac{1}{4}} \exp \left(-f^{2} / \Delta f^{2}\right)  \tag{33}\\
\int|G(f)|^{2} d f=1 \tag{34}
\end{gather*}
$$

Then, the average meter reading $\langle f\rangle$ in Equation 23 is given by:

$$
\begin{equation*}
\langle f\rangle=\frac{A(1)^{2}+2 A(2)^{2}+3 A(1) A(2) e^{-0.5 / \Delta f^{2}}}{A(1)^{2}+A(2)^{2}+2 A(1) A(2) e^{-0.5 / \Delta f^{2}}} \tag{35}
\end{equation*}
$$



Figure 2: The mean meter reading as the function of the accuracy of the measurement in the double slit case of section 9 The freely precessing spin is pre-selected in the state $|1\rangle$ at time $t=0$ and post-selected in the same state $|1\rangle$ at time $t=1.5659 / \omega_{L}$. In the strong measurement regime the meter destroys coherence between the pathways passing through different slits, but also destroys the interference pattern. In the weak regime the interference is intact, but the measured mean slit number is -100 . In the intermediate regime the mean slit number changes smoothly from 1.5 to -100.

Its dependence on $\Delta f$ is shown in Figure 2,
This is, of course, an oversimplified version of the Young's double slit experiment: the states at $t=T / 2$ play the role of the two slits, and the states at $t=T$ play the role of the positions on the screen where an interference pattern is observed.

Consider first a strong measurement of the slit number. Choose the final time such that finding the freely precessing spin in the state $|1\rangle$ is unlikely (our interference pattern has there a minimum), say $T=1.5659 / \omega_{L}$. In the limit $\Delta f \rightarrow 0$, the probability distribution for the meter readings is (cf. Equation 19):

$$
\begin{align*}
& P^{1 \leftarrow 1}(T \mid f)=\cos ^{4}\left(\omega_{L} T / 2\right) \delta(f-1)  \tag{36}\\
&+\sin ^{4}\left(\omega_{L} T / 2\right) \delta(f-2) \\
& \approx 0.252 \delta(f-1)+0.248 \delta(f-2)
\end{align*}
$$

We observe that the two pathways are travelled with almost equal probability, and Equation 35 gives us the mean slit number:

$$
\begin{equation*}
\langle f\rangle_{\text {strong }} \approx 1.5 \tag{37}
\end{equation*}
$$

However, this is not the original spin precession we set out to study. The interference pattern has been destroyed
and the probability to arrive at the final position $|1\rangle$, which without a meter was:

$$
\begin{equation*}
|A(1)+A(2)|^{2} \approx 0.000024 \tag{38}
\end{equation*}
$$

is now close to 0.5 . This is a textbook example which illustrates the uncertainty principle: converting virtual paths into real ones comes at the cost of loosing the interference pattern.

We may now try to minimise the perturbation in the hope to learn something about the route chosen by the system without destroying the interference. In the limit $\Delta f \rightarrow \infty$, after many trials, we will find that the mean number of the slit that has been chosen is:

$$
\begin{equation*}
\langle f\rangle_{\text {weak }}=\operatorname{Re}\left(\frac{1 \times A(1)+2 \times A(2)}{A(1)+A(2)}\right)=-100 \tag{39}
\end{equation*}
$$

This brings us back to our original question, to rephrase the title of [1], "How the result of measuring the number of the slit in a double slit experiment can turn out to be $-100 "$ ?

## 10 Discussion

We have tried to evaluate the mean number of the slit a particle goes through in a double slit experiment, and came up with the number -100 . The mathematics is straightforward, and we need to understand the meaning of this result before employing weak measurements for other purposes. There are just two slits, numbered 1 and 2, so the result looks a bit strange. Has our measurement gone wrong, or is the quantum world so strange that there are slits we are not aware of? We opt for the first choice. (The authors of [5] suggested using weak measurements to analyse the so-called Hardy's paradox. Our analysis of their approach, and of the paradox itself can be found in [15, 16])

Flawed measurements are common in classical physics. They can be made and repeated, but only have meaning within the narrow context of the flawed experiment itself. A broken speedometer may read 50 mph each time the car goes at 100 mph , and might convince the driver, but not the traffic policemen who stops him for speeding. Similarly, the slit number - 100 may come up in a weak measurement, but cannot be used for any other purpose, such as convincing a potential user that the screen he is about to buy has more than two holes drilled in it.

There is, however, one important distinction. Classically, one can always find the right answer and correct, or re-calibrate the errant speedometer. Quantally, it is not so. According to the uncertainty principle, there is no correct answer to the question asked. The nearest classical analogy might be this: suppose a (purely classical) charge can be transferred across one of the two lead wires, and an observer can measure, which one has been chosen. Then the wires are heated up and melted into one. Which of the two wires has the charge gone through now? This is what interference does, it melts the pathways through the two slits into a single one, thus depriving the Which way? question of its meaning.

Weak measurements rely on an interesting interference effect which has applications beyond measurement theory [23, 24]. They can be made, and have been made in practice [2]. They have useful applications in interferometry [7, 8]. However, their results should not be over-interpreted. Bizarre weak values indicate the failure of a measurement procedure under the conditions where, according to the uncertainty principle, it must fail. Seen like this, the weak measurements loose much of their original appeal, and the calculation of weak values reduces to a simple exercise in first order perturbation theory.

In this paper we have discussed situations in which the results of weak measurements should be taken with great care. Especially when the result of a weak measurement turns out to be counterintuitive, we think that
it is important to correctly interpret this result within the general framework of quantum mechanics, and we have emphasized the role of the uncertainty principle in this respect. In particular, counterintuitive weak values might be the sign that our interpretation of the result of a weak measurement has been pushed far beyond what a well posed question is in the context of the quantum theory of measurement. Without providing an answer themselves, weak measurements might help promote the search for more general frameworks, within which fundamental principles of quantum mechanics could find a more natural explanation.

## Acknowledgements

I acknowledge support of the Basque Government (Grant No. IT-472-10), and the Ministry of Science and Innovation of Spain (Grant No. FIS2009-12773-C02-01).

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